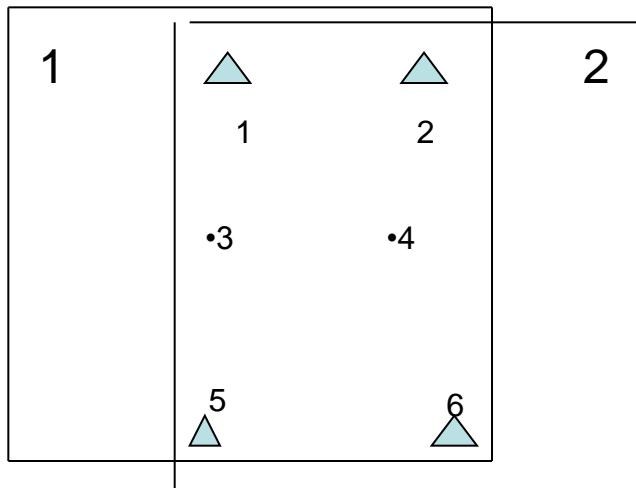


# Observation Equations for 2 photo configuration

$$\begin{array}{l}
 \text{Collinearity} \\
 \text{Camera} \\
 \text{parameters} \\
 \text{GCPs}
 \end{array}
 \left[ \begin{array}{cc}
 \dot{\mathbf{A}} & \ddot{\mathbf{A}} \\
 \mathbf{I} & 0 \\
 0 & \mathbf{I}
 \end{array} \right]
 \left[ \begin{array}{c}
 \Delta \dot{\mathbf{x}} \\
 \Delta \ddot{\mathbf{x}}
 \end{array} \right]
 - \left[ \begin{array}{c}
 \mathbf{b}_1 \\
 \mathbf{b}_2 \\
 \mathbf{b}_3
 \end{array} \right]
 = \left[ \begin{array}{c}
 \mathbf{v} \\
 \mathbf{v}_2 \\
 \mathbf{v}_3
 \end{array} \right]$$



6 points are observed on 2 photos. Camera station positions have been determined by GPS. Points 1, 2, 5 and 6 are GCPs as shown by the triangles.

**One the following page**, the non-zero elements of the above matrices have been shown in their correct locations. There are zeros in all other locations.  
Due to limitations in space, vectors  $\mathbf{b}$  and  $\mathbf{v}$  have not be shown.

# Observation Equations

$$\begin{array}{c}
 \bullet \\
 \textbf{A} \\
 24,12 \\
 \text{Pt Nos} \\
 + \\
 \text{Photo 1} \\
 \left[ \begin{array}{l}
 \begin{bmatrix} a_{11} a_{12} a_{13} a_{14} a_{15} a_{16} \\ a_{21} a_{22} a_{23} a_{24} a_{25} a_{26} \end{bmatrix} 1 \\
 \begin{bmatrix} a_{11} a_{12} a_{13} a_{14} a_{15} a_{16} \\ a_{21} a_{22} a_{23} a_{24} a_{25} a_{26} \end{bmatrix} 2 \\
 \begin{bmatrix} a_{11} a_{12} a_{13} a_{14} a_{15} a_{16} \\ a_{21} a_{22} a_{23} a_{24} a_{25} a_{26} \end{bmatrix} 3 \\
 \begin{bmatrix} a_{11} a_{12} a_{13} a_{14} a_{15} a_{16} \\ a_{21} a_{22} a_{23} a_{24} a_{25} a_{26} \end{bmatrix} 4 \\
 \begin{bmatrix} a_{11} a_{12} a_{13} a_{14} a_{15} a_{16} \\ a_{21} a_{22} a_{23} a_{24} a_{25} a_{26} \end{bmatrix} 5 \\
 \begin{bmatrix} a_{11} a_{12} a_{13} a_{14} a_{15} a_{16} \\ a_{21} a_{22} a_{23} a_{24} a_{25} a_{26} \end{bmatrix} 6
 \end{array} \right] \\
 + \\
 \bullet \\
 \textbf{X} \\
 12,1 \\
 \left[ \begin{array}{l}
 \begin{bmatrix} \Delta X_1^C \\ \Delta Y_1^C \\ \Delta Z_1^C \\ \Delta \omega_1 \\ \Delta \phi_1 \\ \Delta \kappa_1 \\ \Delta X_2^C \\ \Delta Y_2^C \\ \Delta Z_2^C \\ \Delta \omega_2 \\ \Delta \phi_2 \\ \Delta \kappa_2 \end{bmatrix} 1 = \text{pt No} \\
 \begin{bmatrix} a_{17} & a_{18} & a_{19} \\ a_{27} & a_{28} & a_{29} \end{bmatrix} 2 \\
 \begin{bmatrix} a_{17} & a_{18} & a_{19} \\ a_{27} & a_{28} & a_{29} \end{bmatrix} 3 \\
 \begin{bmatrix} a_{17} & a_{18} & a_{19} \\ a_{27} & a_{28} & a_{29} \end{bmatrix} 4 \\
 \begin{bmatrix} a_{17} & a_{18} & a_{19} \\ a_{27} & a_{28} & a_{29} \end{bmatrix} 5 \\
 \begin{bmatrix} a_{17} & a_{18} & a_{19} \\ a_{27} & a_{28} & a_{29} \end{bmatrix} 6
 \end{array} \right] \\
 + \\
 \bullet \\
 \textbf{A} \\
 24,18 \\
 \left[ \begin{array}{l}
 \begin{bmatrix} X_1 \\ Y_1 \\ Z_1 \\ X_2 \\ Y_2 \\ Z_2 \\ X_3 \\ Y_3 \\ Z_3 \\ X_4 \\ Y_4 \\ Z_4 \\ X_5 \\ Y_5 \\ Z_5 \\ X_6 \\ Y_6 \\ Z_6 \end{bmatrix} 18,1
 \end{array} \right]
 \end{array}$$

0

Eqns for Camera stn obs [6,12]

Eqns for GCPs [12,18]